

### MLFB-Ordering data

6SL3210-1KE24-4UF1



Client order no. : Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	41.00 A	
Rated current (HO)	39.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC 480V NEC	

Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC
Rated power (LO)	22.00 kW	25.00 hp
Rated power (HO)	18.50 kW	20.00 hp
Rated current (LO)	43.00 A	
Rated current (HO)	37.00 A	
Rated current (IN)	43.00 A	
Max. output current	74.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability	
Low Overload (LO)	
150 % base load current IL for 3 s, followed by 110 % ba	se load current IL for 57 s in a

300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor $\lambda$	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	0.68 kW	
Filter class (integrated)	Unfiltered	

Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.055 m³/s (1.942 ft³/s)		
Installation altitude	1000 m (3280.84 ft)		
Ambient temperature			
Operation	-20 40 °C (-4 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			

## Max. operation 95 % RH, condensation not permitted

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
Size	FSD	Connections		
Net weight	17.10 kg (37.70 lb)	Signal cable		
Width	200 mm (7.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 A	
Height	472 mm (18.58 in)	Line side		
Depth	237 mm (9.33 in)	Version	screw-type terminal	
Inputs / out	tputs	Conductor cross-section	10.00 35.00 mm² (AWG 8	
tandard digital inputs		Motor end		
Number	6	Version	Screw-type terminals	
Switching level: 0→1	11 V	Conductor cross-section	10.00 35.00 mm² (AWG 8 A	
Switching level: 1→0	5 V	DC link (for braking resistor)	) 	
Max. inrush current	15 mA	Version	Screw-type terminals	
ail-safe digital inputs		Conductor cross-section	10.00 35.00 mm² (AWG 8 A	
Number	1	Line length, max.	10 m (32.81 ft)	
Digital outputs		PE connection	Screw-type terminals	
Number as relay changeover contact	1	Max. motor cable length	Second type terminals	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)	
Number as transistor	1	Unshielded	300 m (984.25 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	tandards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low Directive 2006/95/EC	
Switching threshold as digital inp	out			
0→1	4 V			
1→0	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			

## PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 



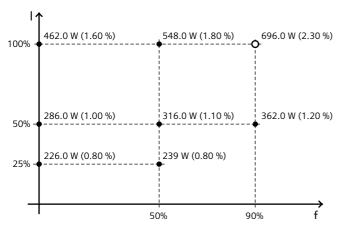
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## Converter losses to IEC61800-9-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	48.00 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values